**Automated Lane Simulation**

**A Major Project Report Submitted to**



**Rajiv Gandhi Proudyogiki Vishwavidyalaya, Bhopal Towards Partial Fulfillment for the Award of**

**Bachelor of Engineering**

**(Information Technology)**

**Under the Supervision of Submitted By**

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December 2019

**EXAMINER APPROVAL**

***The Project entitled “Automated Lane Simulation”*submitted by Raksha Sankhala**(0827IT161086)**, Saiel Wadwekar** (0827IT161094)**, Saquib Qureshi** (0827IT161098), **Yashasvi Sharma** (0827IT161121), **Yashraj Sharma** (0827IT161122), **Yuvraj Singh Panwar** (0827IT161123)has been examined and is hereby approved towards partial fulfillment for the award of ***Bachelor of Engineering degree in Information Technology***discipline, for which it has been submitted. It understood that by this approval the undersigned do not necessarily endorse or approve any statement made, opinion expressed or conclusion drawn therein, but approve the project only for the purpose for which it has been submitted.

|  |  |
| --- | --- |
| **(Internal Examiner)** | **(External Examiner)** |
| **Date:** | **Date:** |

**GUIDE RECOMMENDATION**

This is to certify that the work embodied in this project entitled **“Automated Lane Simulation”** Submitted by**Raksha Sankhala**(0827IT161086), **Saquib Qureshi**(0827IT161098), **Saiel Wadwekar** (0827IT16094),**Yashasvi Sharma**(0827IT161121), **Yashraj Sharma** (0827IT161122), **Yuvraj Singh Panwar** (0827It161123) is a satisfactory account of the bonafide work, done under the supervision of **Prof. Pawan Gupta**, is recommended towards partial fulfillment for the award of the **Bachelor of Engineering (Information Technology)** degree by **Rajiv Gandhi Proudyogiki Vishwavidhyalaya, Bhopal.**

**(Project Guide) (Project Coordinator)**

**STUDENTS UNDERTAKING**

This is to certify that project entitled “**Automated Lane Simulation**” has developed by us in the supervision of **Prof. Pawan K Gupta**. The whole responsibility of work done in this project is ours. The sole intension of this work is only for practical learning and research. However, we put proper citation remarks in our work. If the same work found then we are liable for explanation to this.

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**ACKNOWLEDGEMENT**

We thank the almighty Lord for giving us the strength and courage to sail out through the tough and reach on shore safely.

There are number of people without whom this projects work would not have been feasible. Their high academic standards and personal integrity provided me with continuous guidance and support.

We owe a debt of sincere gratitude, deep sense of reverence and respect to our guide and mentor **Prof. Pawan K Gupta,**for his motivation, sagacious guidance, constant encouragement, vigilant supervision and valuable critical appreciation throughout this project work, which helped us to successfully complete the project on time.

We express profound gratitude and heartfelt thanks to **Prof. Pawan K Gupta**, for his support, suggestion and inspiration for carrying out this project. I am very much thankful to other faculty and staff members of IT Dept, AITR Indore for providing me all support, help and advice during the project. We would be failing in our duty if do not acknowledge the support and guidance received from **Dr. S C Sharma**, Director, AITR, Indore whenever needed. We take opportunity to convey my regards to the management of Acropolis Institute, Indore for extending academic and administrative support and providing me all necessary facilities for project to achieve our objectives.

We are grateful to **our parent**and **family members**who have always loved and supported us unconditionally. To all of them, we want to say “Thank you”, for being the best family that one could ever have and without whom none of this would have been possible.

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SUMMARY

***Automated Lane Simulation***

This project is submitted to Rajiv Gandhi Proudyogiki Vishwavidhyalaya, Bhopal(MP), India for partial fulfilment of Bachelor of Engineering in Information Technology branch under the sagacious guidance and vigilant supervision of **Prof. Pawan Kumar Gupta**.

In this paper, we propose a lane detection method that is suitable for all kinds of complex traffic situations, especially as driving speed in roads is too fast. First, we pre-processed each frame image and then selected the area of interest (ROI) of the processed images. Finally, we only needed edge detection vehicle and line detection for the ROI area. In this study, we introduced a new pre-processing method and ROI selection method. First, in the pre-processing stage, we converted the RGB colour model to the HSV colour space model and extracted white features on the HSV model. At the same time, the preliminary edge feature detection is added in the pre-processing stage, and then the part below the image is selected as the ROI area based on the proposed pre-processing. Compared with the existing methods, the existing pre-processing methods only perform operations such as graying, blurring, X-gradient, Y-gradient, global gradient, thresh, and morphological closure. And the ways to select the ROI area are also very different. Some of them are based on the edge feature of the lane to select the ROI area, and some are based on the colour feature of the lane to select the ROI area. These existing methods do not provide accurate and fast lane information, which increases the difficulty of lane detection. In this paper, experiments show that the proposed method is significantly better than the existing pre-processing method and ROI selection method in lane detection.

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